

# Chapter 10

## Simple Harmonic Motion and Elasticity

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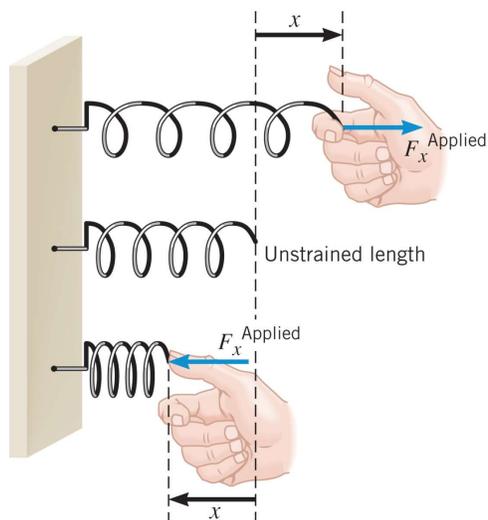
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### 10.1 The Ideal Spring and Simple Harmonic Motion

$$F_x^{Applied} = kx$$

spring constant

Units: N/m



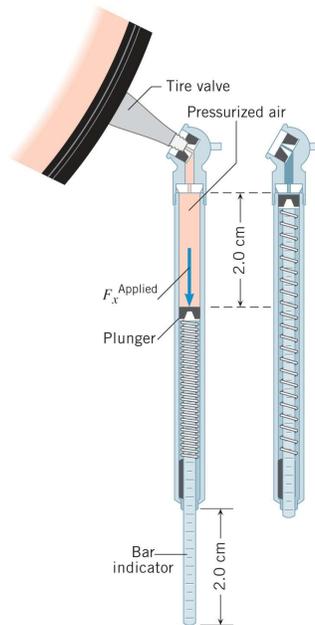
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## 10.1 The Ideal Spring and Simple Harmonic Motion

**Example 1 A Tire Pressure Gauge**

The spring constant of the spring is 320 N/m and the bar indicator extends 2.0 cm. What force does the air in the tire apply to the spring?



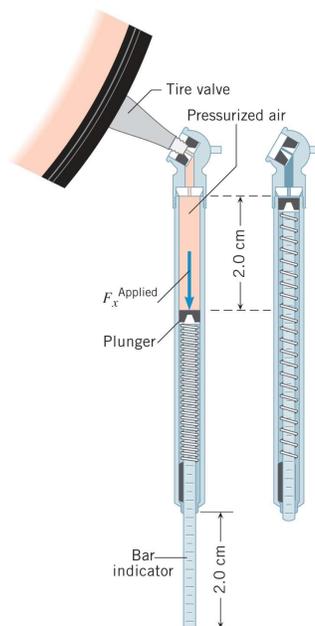
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## 10.1 The Ideal Spring and Simple Harmonic Motion

$$F_x^{Applied} = kx$$

$$= (320 \text{ N/m})(0.020 \text{ m}) = 6.4 \text{ N}$$



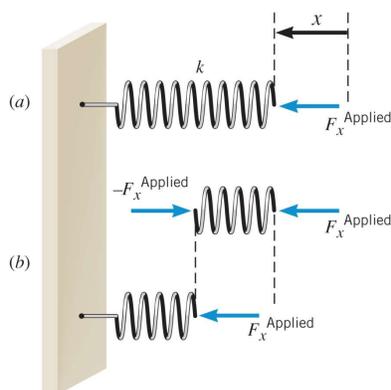
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10.1 The Ideal Spring and Simple Harmonic Motion

**Conceptual Example 2 Are Shorter Springs Stiffer?**

A 10-coil spring has a spring constant  $k$ . If the spring is cut in half, so there are two 5-coil springs, what is the spring constant of each of the smaller springs?



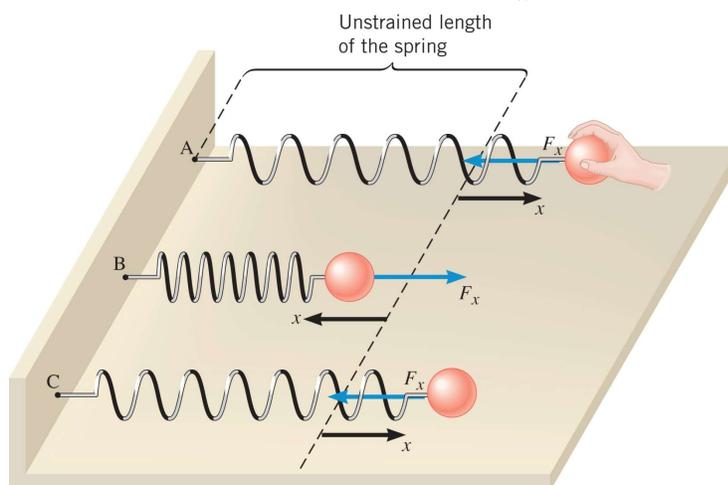
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10.1 The Ideal Spring and Simple Harmonic Motion

**HOOKE'S LAW: RESTORING FORCE OF AN IDEAL SPRING**

The restoring force on an ideal spring is  $F_x = -kx$

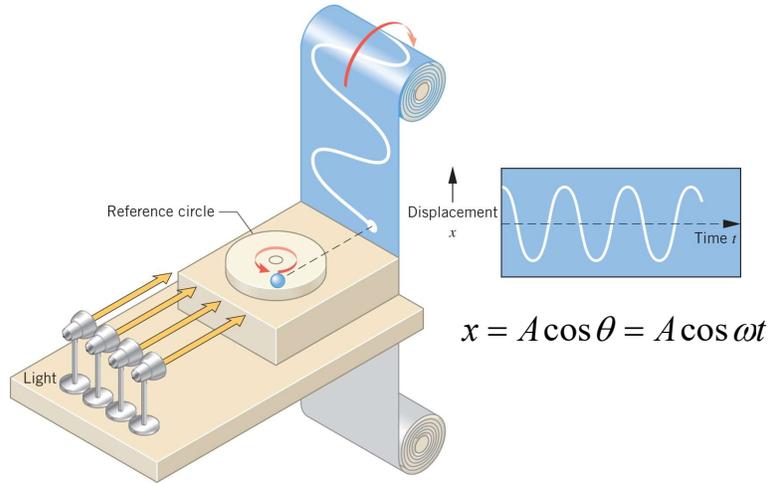


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10.2 Simple Harmonic Motion and the Reference Circle

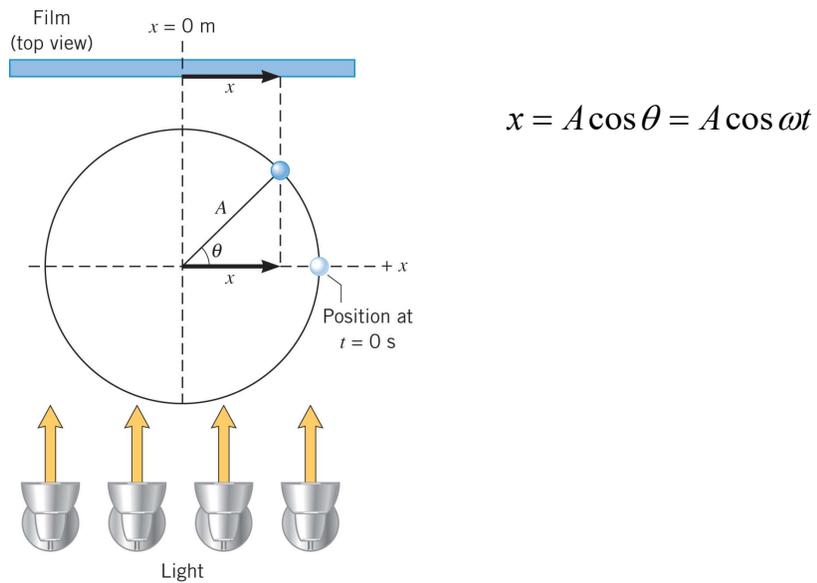
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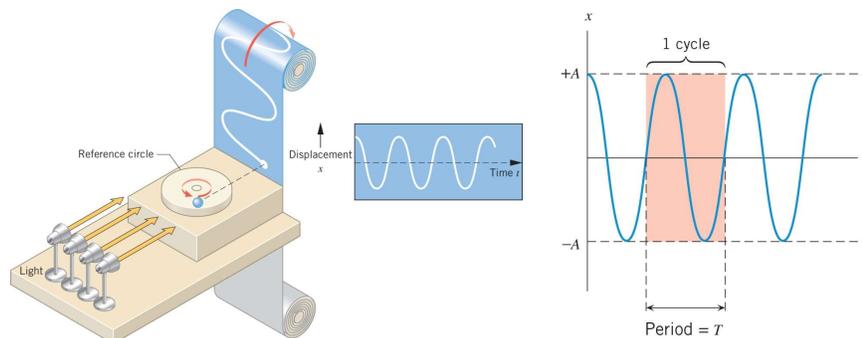
10.2 Simple Harmonic Motion and the Reference Circle



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10.2 Simple Harmonic Motion and the Reference Circle



**amplitude A:** the maximum displacement

**period T:** the time required to complete one cycle

**frequency f:** the number of cycles per second (measured in Hz)

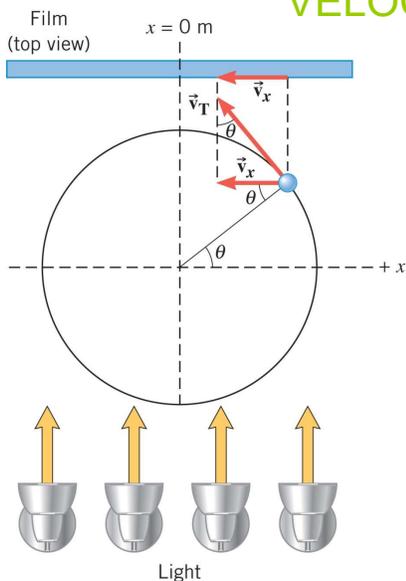
$$f = \frac{1}{T} \qquad \omega = 2\pi f = \frac{2\pi}{T}$$

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10.2 Simple Harmonic Motion and the Reference Circle

VELOCITY



$$v_x = -v_T \sin \theta = -\underbrace{A\omega}_{v_{\max}} \sin \omega t$$

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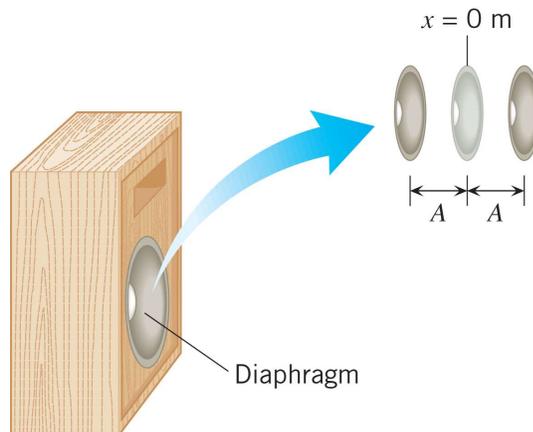
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## 10.2 Simple Harmonic Motion and the Reference Circle

**Example 3 The Maximum Speed of a Loudspeaker Diaphragm**

The frequency of motion is 1.0 KHz and the amplitude is 0.20 mm.

- (a) What is the maximum speed of the diaphragm?  
 (b) Where in the motion does this maximum speed occur?



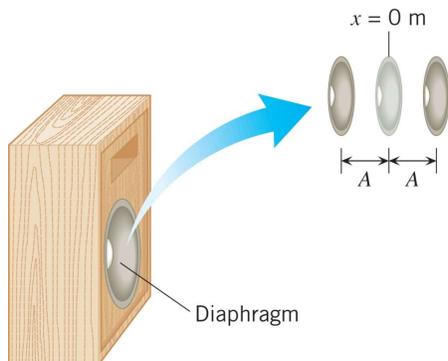
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## 10.2 Simple Harmonic Motion and the Reference Circle

$$v_x = -v_T \sin \theta = -\underbrace{A\omega}_{v_{\max}} \sin \omega t$$

(a)  $v_{\max} = A\omega = A(2\pi f) = (0.20 \times 10^{-3} \text{ m})(2\pi)(1.0 \times 10^3 \text{ Hz})$   
 $= 1.3 \text{ m/s}$



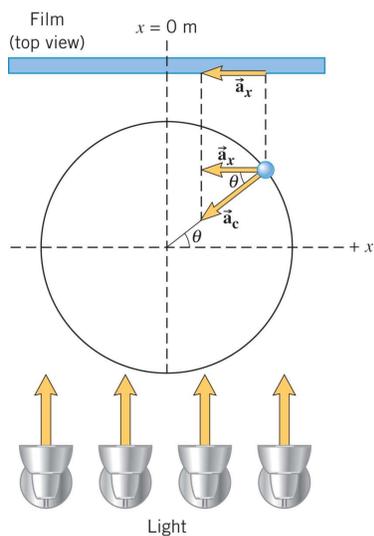
- (b) The maximum speed occurs midway between the ends of its motion.

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## 10.2 Simple Harmonic Motion and the Reference Circle

## ACCELERATION



$$a_x = -a_c \cos \theta = -\underbrace{A\omega^2}_{a_{\max}} \cos \omega t$$

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## 10.2 Simple Harmonic Motion and the Reference Circle

## FREQUENCY OF VIBRATION

$$x = A \cos \omega t$$

$$a_x = -A\omega^2 \cos \omega t$$

$$\sum F = -kx = ma_x$$

$$-kA = -mA\omega^2$$

$$\omega = \sqrt{\frac{k}{m}}$$

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### 10.2 Simple Harmonic Motion and the Reference Circle

#### Example 6 A Body Mass Measurement Device

The device consists of a spring-mounted chair in which the astronaut sits. The spring has a spring constant of 606 N/m and the mass of the chair is 12.0 kg. The measured period is 2.41 s. Find the mass of the astronaut.



Courtesy NASA

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### 10.2 Simple Harmonic Motion and the Reference Circle

$$\omega = \sqrt{\frac{k}{m_{\text{total}}}} \quad \longrightarrow \quad m_{\text{total}} = k/\omega^2$$

$$\omega = 2\pi f = \frac{2\pi}{T}$$

$$m_{\text{total}} = \frac{k}{(2\pi/T)^2} = m_{\text{chair}} + m_{\text{astro}}$$

$$m_{\text{astro}} = \frac{k}{(2\pi/T)^2} - m_{\text{chair}}$$

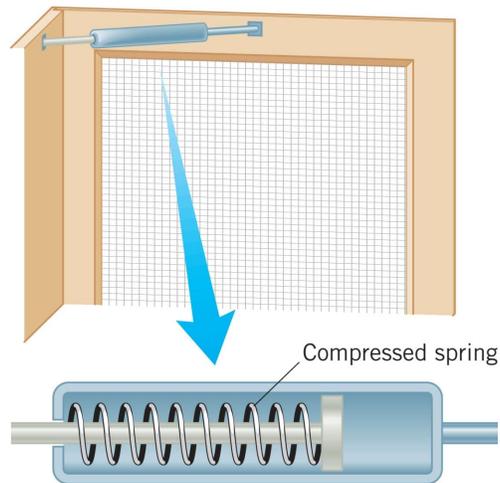
$$= \frac{(606 \text{ N/m})(2.41 \text{ s})^2}{4\pi^2} - 12.0 \text{ kg} = 77.2 \text{ kg}$$

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## 10.3 Energy and Simple Harmonic Motion

A compressed spring can do work.



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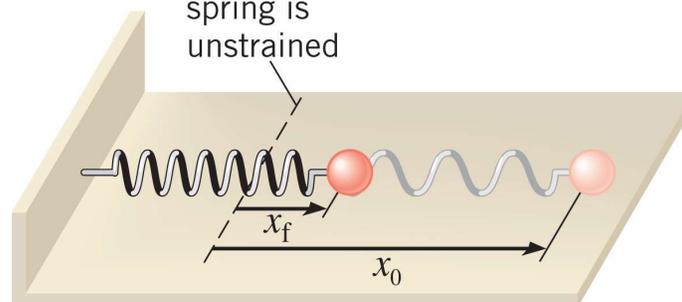
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## 10.3 Energy and Simple Harmonic Motion

$$W_{\text{elastic}} = (\bar{F} \cos \theta) s = \frac{1}{2} (kx_o + kx_f) \cos 0^\circ (x_o - x_f)$$

$$W_{\text{elastic}} = \frac{1}{2} kx_o^2 - \frac{1}{2} kx_f^2$$

Position when  
spring is  
unstrained



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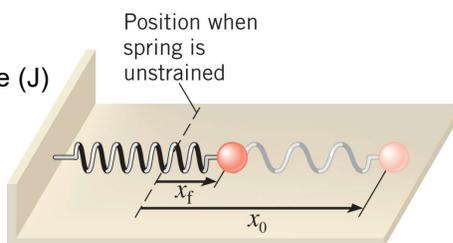
## 10.3 Energy and Simple Harmonic Motion

## DEFINITION OF ELASTIC POTENTIAL ENERGY

The elastic potential energy is the energy that a spring has by virtue of being stretched or compressed. For an ideal spring, the elastic potential energy is

$$PE_{\text{elastic}} = \frac{1}{2} kx^2$$

**SI Unit of Elastic Potential Energy:** joule (J)



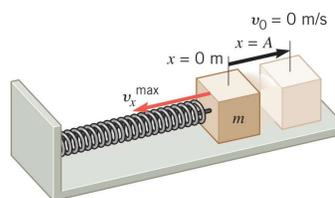
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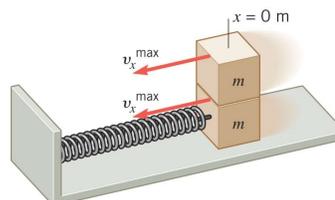
## 10.3 Energy and Simple Harmonic Motion

**Conceptual Example 8** Changing the Mass of a Simple Harmonic Oscillator

The box rests on a horizontal, frictionless surface. The spring is stretched to  $x=A$  and released. When the box is passing through  $x=0$ , a second box of the same mass is attached to it. Discuss what happens to the (a) maximum speed (b) amplitude (c) angular frequency.



(a)



(b)

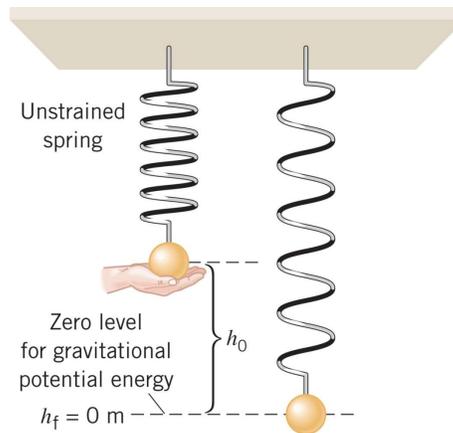
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## 10.3 Energy and Simple Harmonic Motion

**Example 8 Adding a Mass to a Simple Harmonic Oscillator**

A 0.20-kg ball is attached to a vertical spring. The spring constant is 28 N/m. When released from rest, how far does the ball fall before being brought to a momentary stop by the spring?



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## 10.3 Energy and Simple Harmonic Motion

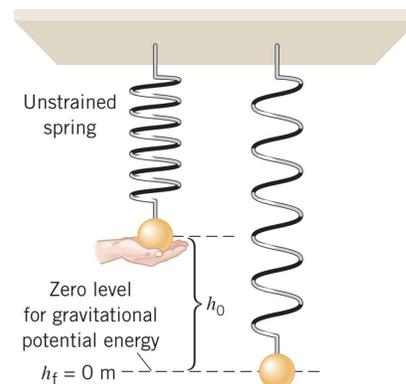
$$E_f = E_o$$

$$\frac{1}{2}mv_f^2 + \frac{1}{2}I\omega_f^2 + mgh_f + \frac{1}{2}ky_f^2 = \frac{1}{2}mv_o^2 + \frac{1}{2}I\omega_o^2 + mgh_o + \frac{1}{2}ky_o^2$$

$$\frac{1}{2}kh_o^2 = mgh_o$$

$$h_o = \frac{2mg}{k}$$

$$= \frac{2(0.20 \text{ kg})(9.8 \text{ m/s}^2)}{28 \text{ N/m}} = 0.14 \text{ m}$$



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**10.4 The Pendulum**

A **simple pendulum** consists of a particle attached to a frictionless pivot by a cable of negligible mass.

$$\omega = \sqrt{\frac{g}{L}} \quad (\text{small angles only})$$

Physical pendulum

$$\omega = \sqrt{\frac{mgL}{I}} \quad (\text{small angles only})$$

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**10.4 The Pendulum****Example 10 Keeping Time**

Determine the length of a simple pendulum that will swing back and forth in simple harmonic motion with a period of 1.00 s.

$$\omega = 2\pi f = \frac{2\pi}{T} = \sqrt{\frac{g}{L}} \quad \longrightarrow \quad L = \frac{T^2 g}{4\pi^2}$$

$$L = \frac{T^2 g}{4\pi^2} = \frac{(1.00 \text{ s})^2 (9.80 \text{ m/s}^2)}{4\pi^2} = 0.248 \text{ m}$$

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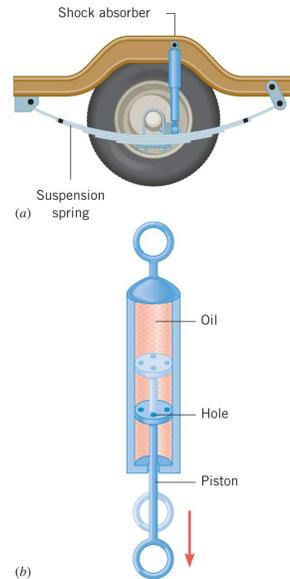
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### 10.5 Damped Harmonic Motion

In simple harmonic motion, an object oscillates with a constant amplitude.

In reality, friction or some other energy dissipating mechanism is always present and the amplitude decreases as time passes.

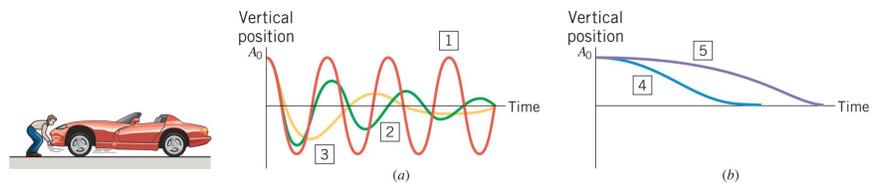
This is referred to as **damped harmonic motion**.



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### 10.5 Damped Harmonic Motion



- 1) simple harmonic motion
- 2&3) underdamped
- 4) critically damped
- 5) overdamped

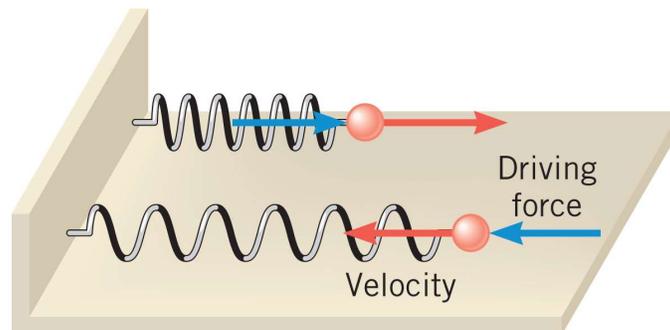
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### 10.6 Driven Harmonic Motion and Resonance

When a force is applied to an oscillating system at all times, the result is **driven harmonic motion**.

Here, the driving force has the same frequency as the spring system and always points in the direction of the object's velocity.



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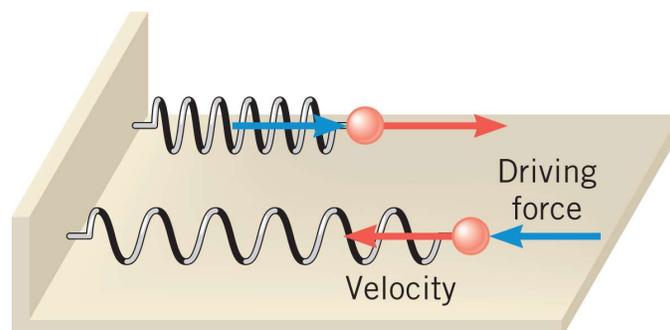
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### 10.6 Driven Harmonic Motion and Resonance

#### RESONANCE

Resonance is the condition in which a time-dependent applied force can transmit large amounts of energy to an oscillating object, leading to a large amplitude motion.

Resonance occurs when the frequency of the applied force matches a natural frequency at which the object will oscillate.

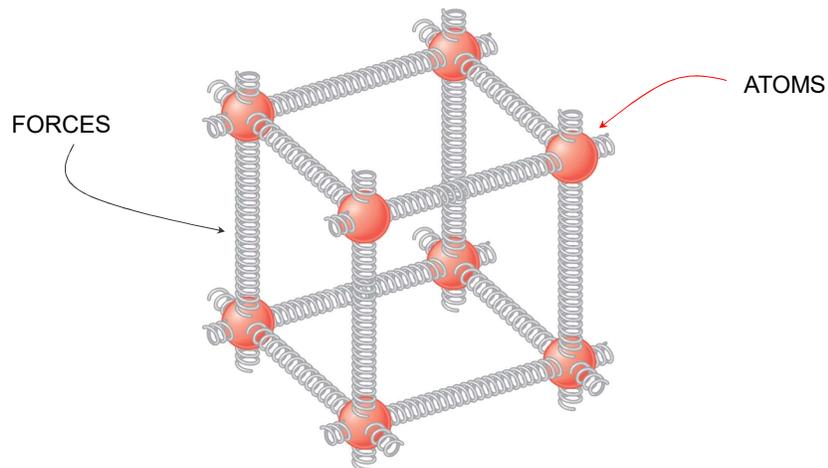


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### 10.7 Elastic Deformation

Because of these atomic-level “springs”, a material tends to return to its initial shape once forces have been removed.

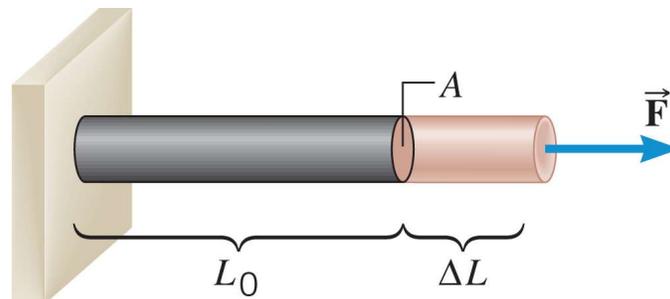


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### 10.7 Elastic Deformation

#### STRETCHING, COMPRESSION, AND YOUNG'S MODULUS



$$F = Y \left( \frac{\Delta L}{L_0} \right) A$$

Young's modulus has the units of pressure:  $\text{N/m}^2$

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### 10.7 Elastic Deformation

**Table 10.1** Values for the Young's Modulus of Solid Materials

Material	Young's Modulus $Y$ (N/m <sup>2</sup> )
Aluminum	$6.9 \times 10^{10}$
Bone	
Compression	$9.4 \times 10^9$
Tension	$1.6 \times 10^{10}$
Brass	$9.0 \times 10^{10}$
Brick	$1.4 \times 10^{10}$
Copper	$1.1 \times 10^{11}$
Mohair	$2.9 \times 10^9$
Nylon	$3.7 \times 10^9$
Pyrex glass	$6.2 \times 10^{10}$
Steel	$2.0 \times 10^{11}$
Teflon	$3.7 \times 10^8$
Titanium	$1.2 \times 10^{11}$
Tungsten	$3.6 \times 10^{11}$

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### 10.7 Elastic Deformation

#### Example 12 Bone Compression

In a circus act, a performer supports the combined weight (1080 N) of a number of colleagues. Each thighbone of this performer has a length of 0.55 m and an effective cross sectional area of  $7.7 \times 10^{-4} \text{ m}^2$ . Determine the amount that each thighbone compresses under the extra weight.



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## 10.7 Elastic Deformation

$$F = Y \left( \frac{\Delta L}{L_o} \right) A$$



$$\Delta L = \frac{FL_o}{YA} = \frac{(540 \text{ N})(0.55 \text{ m})}{(9.4 \times 10^9 \text{ N/m}^2)(7.7 \times 10^{-4} \text{ m}^2)} = 4.1 \times 10^{-5} \text{ m}$$



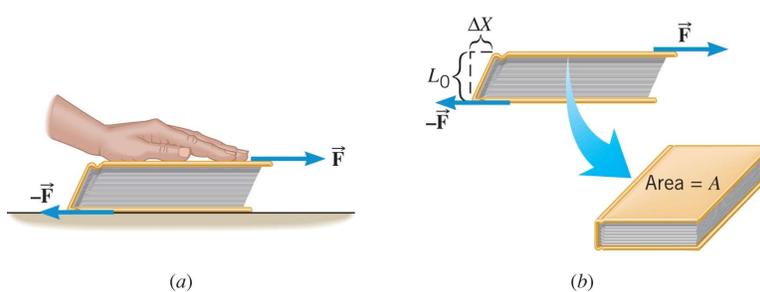
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## 10.7 Elastic Deformation

## SHEAR DEFORMATION AND THE SHEAR MODULUS



$$F = S \left( \frac{\Delta x}{L_o} \right) A$$

The shear modulus has the units of pressure:  $\text{N/m}^2$

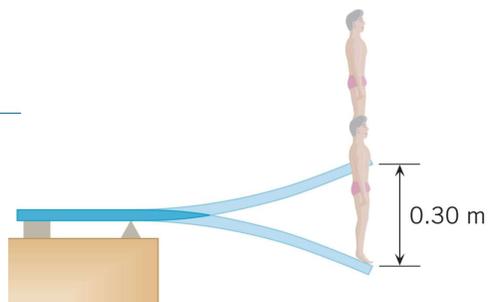
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## 10.7 Elastic Deformation

**Table 10.2** Values for the Shear Modulus of Solid Materials

Material	Shear Modulus $S$ (N/m <sup>2</sup> )
Aluminum	$2.4 \times 10^{10}$
Bone	$1.2 \times 10^{10}$
Brass	$3.5 \times 10^{10}$
Copper	$4.2 \times 10^{10}$
Lead	$5.4 \times 10^9$
Nickel	$7.3 \times 10^{10}$
Steel	$8.1 \times 10^{10}$
Tungsten	$1.5 \times 10^{11}$



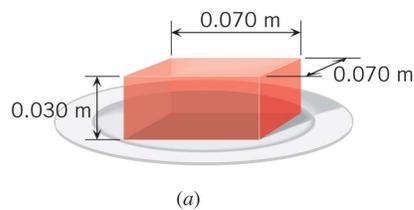
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## 10.7 Elastic Deformation

**Example 14 J-E-L-L-O**

You push tangentially across the top surface with a force of 0.45 N. The top surface moves a distance of 6.0 mm relative to the bottom surface. What is the shear modulus of Jell-O?

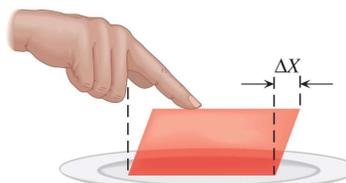


(a)

$$F = S \left( \frac{\Delta x}{L_o} \right) A$$



$$S = \frac{FL_o}{A\Delta x}$$

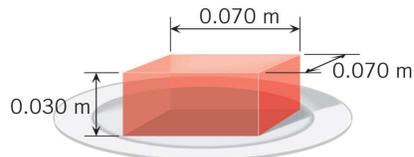


(b)

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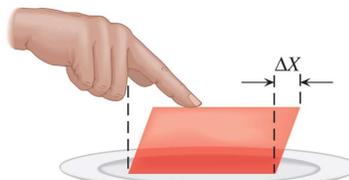
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10.7 Elastic Deformation



(a)

$$S = \frac{FL_o}{A\Delta x}$$



(b)

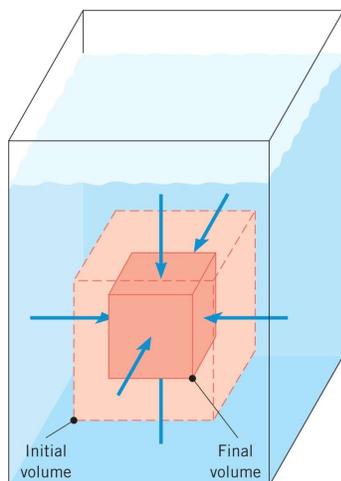
$$S = \frac{(0.45 \text{ N})(0.030 \text{ m})}{(0.070 \text{ m})^2 (6.0 \times 10^{-3} \text{ m})} = 460 \text{ N/m}^2$$

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10.7 Elastic Deformation

VOLUME DEFORMATION AND THE BULK MODULUS



$$\Delta P = -B \left( \frac{\Delta V}{V_o} \right)$$

The Bulk modulus has the units of pressure: N/m<sup>2</sup>

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**10.7 Elastic Deformation****Table 10.3** Values for the Bulk Modulus of Solid and Liquid Materials

Material	Bulk Modulus $B$ [N/m <sup>2</sup> (=Pa)]
<i>Solids</i>	
Aluminum	$7.1 \times 10^{10}$
Brass	$6.7 \times 10^{10}$
Copper	$1.3 \times 10^{11}$
Diamond	$4.43 \times 10^{11}$
Lead	$4.2 \times 10^{10}$
Nylon	$6.1 \times 10^9$
Osmium	$4.62 \times 10^{11}$
Pyrex glass	$2.6 \times 10^{10}$
Steel	$1.4 \times 10^{11}$
<i>Liquids</i>	
Ethanol	$8.9 \times 10^8$
Oil	$1.7 \times 10^9$
Water	$2.2 \times 10^9$

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**10.8 Stress, Strain, and Hooke's Law**

In general the quantity  $F/A$  is called the **stress**.

The change in the quantity divided by that quantity is called the strain:

$$\Delta V/V_o \quad \Delta L/L_o \quad \Delta x/L_o$$

**HOOKE'S LAW FOR STRESS AND STRAIN**

Stress is directly proportional to strain.

Strain is a unitless quantity.

**SI Unit of Stress:** N/m<sup>2</sup>

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